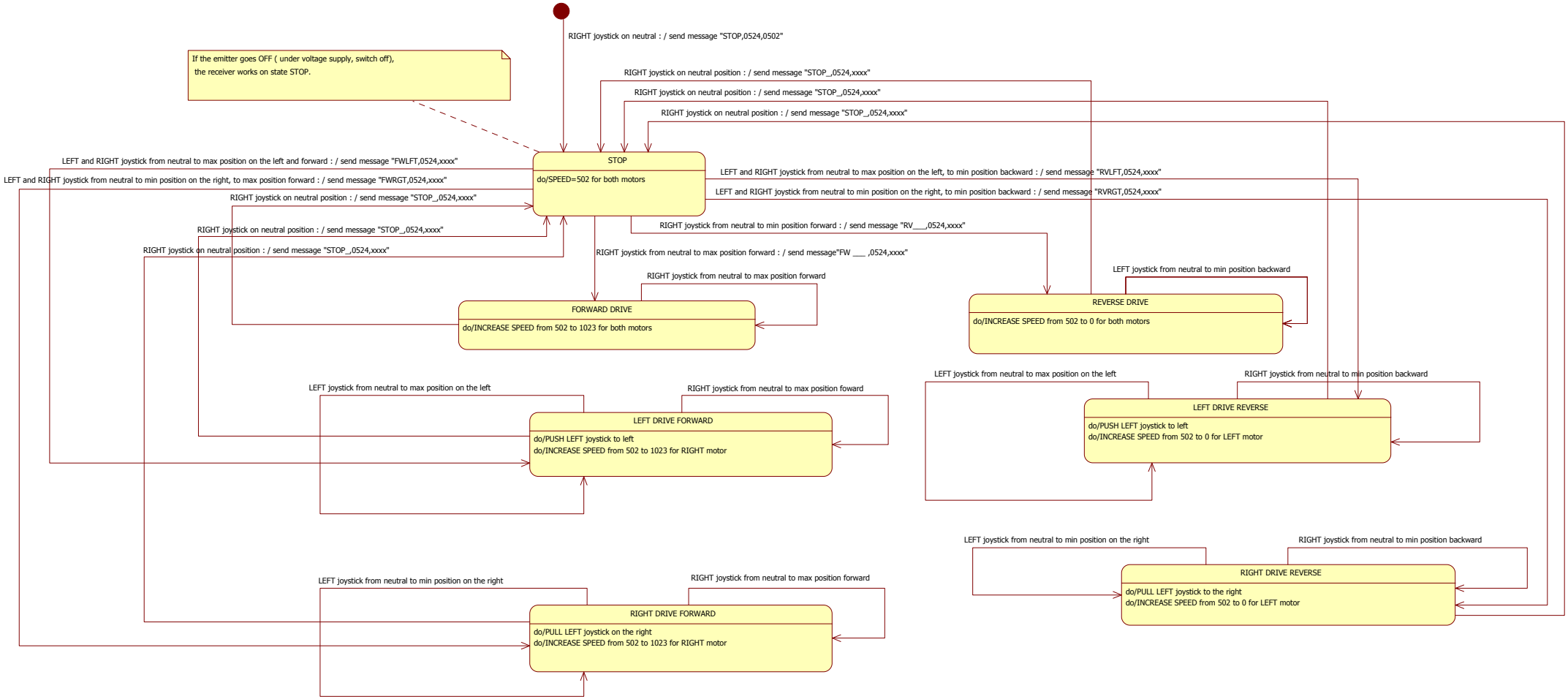
RIGHT joystick on neutral : / send message "STOP,0524,0502"
If the emitter goes OFF (under voltage supply, switch off),
the receiver works on state STOP.
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
LEFT and RIGHT joystick from neutral to max position on the left and forward : / send message "FWLFT,0524,xxxx"
LEFT and RIGHT joystick from neutral to min position on the right, to max position forward : / send message "FWRGT,0524,xxxx"
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
RIGHT joystick on neutral position : / send message "STOP_,0524,xxxx"
STOP
do/SPEED=502 for both motors
LEFT and RIGHT joystick from neutral to max position on the left, to min position backward : / send message "RVLFT,0524,xxxx"
LEFT and RIGHT joystick from neutral to min position on the right, to min position backward : / send message "RVRGT,0524,xxxx"
RIGHT joystick from neutral to min position forward : / send message "RV___,0524,xxxx"
RIGHT joystick from neutral to max position forward : / send message"FW ___ ,0524,xxxx"
RIGHT joystick from neutral to max position forward
FORWARD DRIVE
do/INCREASE SPEED from 502 to 1023 for both motors
LEFT joystick from neutral to min position backward
REVERSE DRIVE
do/INCREASE SPEED from 502 to 0 for both motors
LEFT joystick from neutral to max position on the left
RIGHT joystick from neutral to max position foward
LEFT DRIVE FORWARD
do/PUSH LEFT joystick to left
do/INCREASE SPEED from 502 to 1023 for RIGHT motor
LEFT joystick from neutral to max position on the left
RIGHT joystick from neutral to min position backward
LEFT DRIVE REVERSE
do/PUSH LEFT joystick to left
do/INCREASE SPEED from 502 to 0 for LEFT motor
LEFT joystick from neutral to min position on the right
RIGHT joystick from neutral to min position backward
RIGHT DRIVE REVERSE
do/PULL LEFT joystick to the right
do/INCREASE SPEED from 502 to 0 for LEFT motor
LEFT joystick from neutral to min position on the right
RIGHT joystick from neutral to max position forward
RIGHT DRIVE FORWARD
do/PULL LEFT joystick on the right
do/INCREASE SPEED from 502 to 1023 for RIGHT motor