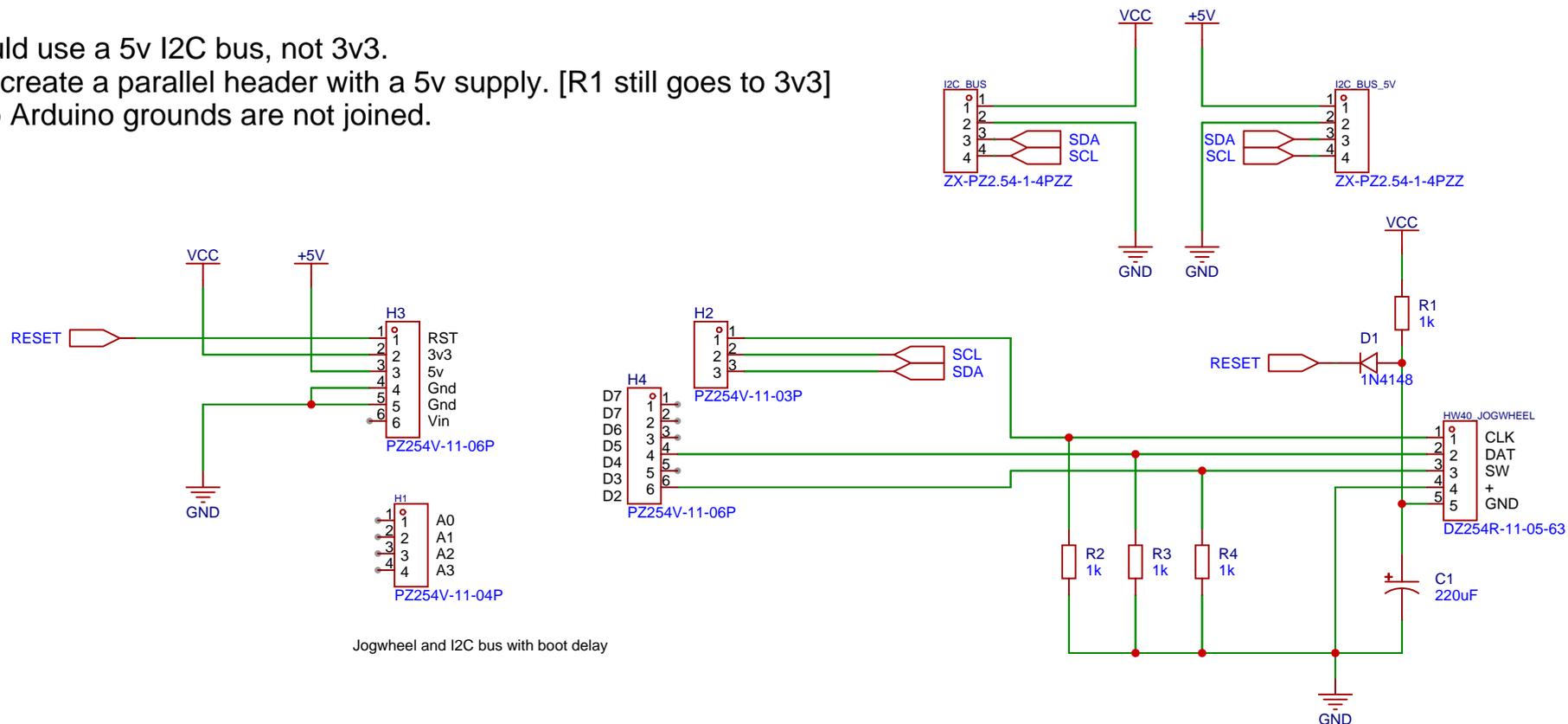


ERRATA:

Design should use a 5v I2C bus, not 3v3.

The fix is to create a parallel header with a 5v supply. [R1 still goes to 3v3]

Also the two Arduino grounds are not joined.



Jogwheel and I2C bus with boot delay

Used NodeMCU Amica2 as the base footprint, emulated it with headers then deleted it off the board, else you create two board headers

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