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// Sheep Doorbell
// May 2011 by Todd Miller based on Adafruit example code
// Plays one sound when sensor is triggered, in this case sheep baaing Uses 7
// sounds and picks one at random
// Parts include Arduino Uno, WAV Shield, small 8 ohm speaker and Sharp
// GP2Y0A02 distance sensor
// To be mounted inside a Shaun The Sheep from Wallace & Gromet

#include <AF_Wave.h>
#include <avr/pgmspace.h>
#include "util.h"
#include "wave.h"
AF_Wave card;
File f;
Wavefile wave; // only one!
uint8_t tracknum = 0;
uint16_t samplerate;

#define sensorIn 0
int songCount = 7;
int a[5];
int results;
int i=0;
int maxDist = 0;
int sensorRead = 0;
int fr = 0;
long previousMillis = 0;
long interval = 3000;

void setup() {
  Serial.begin(9600); // set up Serial library at 9600 bps
  randomSeed(analogRead(1));
  Serial.println("Wave test!");
  pinMode(2, OUTPUT);
  pinMode(3, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(5, OUTPUT);
  pinMode(sensorIn, INPUT);
  if (!card.init_card()) {
    putstring_nl("Card init. failed!"); return;
  }
  if (!card.open_partition()) {
    putstring_nl("No partition!"); return;
  }
  if (!card.open_filesys()) {
    putstring_nl("Couldn't open filesys"); return;
  }
}

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        }
        if (!card.open_rootdir()) {
            putstring_nl("Couldn't open dir"); return;
        }
        putstring_nl("Files found:");
        ls();

        for (i=0; i<5; i++) {          // Get max distance for comparison later
//        maxDist += analogRead(5);
        a[i]+=analogRead(sensorIn);
    }
    insertionSort(a,5);
    ls();
}

void loop() {
    readSensor();
    uint8_t i, r;
    char c, name[15];
    unsigned long currentMillis = millis();

    if(sensorRead > (maxDist +20) && (currentMillis - previousMillis > interval)){
        previousMillis = currentMillis;
        Serial.println(maxDist-25);
        int songNumber = random(songCount);
        Serial.print("Playing track # ");
        Serial.print(songNumber);
        Serial.print(" ");
        Serial.println(name);
        switch(songNumber)
        {
            case 0:
                playcomplete("BAA1.WAV");
                break;
            case 1:
                playcomplete("BAA2.WAV");
                break;
            case 2:
                playcomplete("BAA3.WAV");
                break;
            case 3:
                playcomplete("BAA4.WAV");
                break;
            case 4:
                playcomplete("BAA5.WAV");
        }
    }
}

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break;
case 5:
playcomplete("BAA6.WAV");
break;
case 6:
playcomplete("BAA7.WAV");
break;
}
sensorRead=0;
}
card.reset_dir();
}

void playcomplete(char *name) {
uint16_t potval;
uint32_t newsamplerate;
playfile(name);
samplerate = wave.dwSamplesPerSec;
while (waveisplaying) {
// you can do stuff here!
delay(50);
}
card.close_file(f);
}

void playfile(char *name) {
f = card.open_file(name);
if (!f) {
putstring_nl(" Couldn't open file"); return;
}
if (!wave.create(f)) {
putstring_nl(" Not a valid WAV"); return;
}
// ok time to play!
wave.play();
}
void readSensor(){
for (int i=0; i < 5; i++){
a[i]=analogRead(sensorIn);
}

insertionSort(a,5);
Serial.print("max dis = ");
Serial.println(maxDist);
Serial.print("--- final sensor value = ");

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Serial.print(sensorRead);
Serial.println(" ---");
}

void insertionSort(int arr[], int length) {
    int i;
    int j;
    int tmp;
    for (i = 1; i < length; i++) {
        j = i;
        while (j > 0 && arr[j - 1] > arr[j]) {
            tmp = arr[j];
            arr[j] = arr[j - 1];
            arr[j - 1] = tmp;
            j--;
        }
    }
    // array sorted, now lose low and high values for better average
    a[0]=0;
    a[4]=0;
    for (i = 0; i < 5; i++){
        results= results+a[i];
    }
    results/=3; // divide by 3 as places 1 and 5 = 0
    if (fr == 0)
    {
        maxDist = results;
        fr = 1;
    }
    else sensorRead=results;
    results=0;
}

void ls() {
    char name[13];
    int ret;
    card.reset_dir();
    putstring_nl("Files found:");
    while (1) {
        ret = card.get_next_name_in_dir(name);
        if (!ret) {
            card.reset_dir();
            return;
        }
        Serial.println(name);
    }
}

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}